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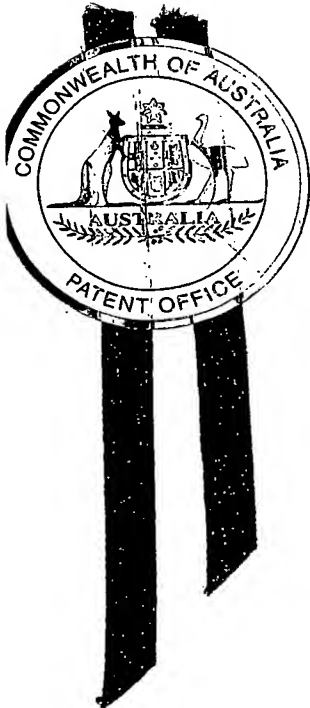
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*J R Yabsley*

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PROVISIONAL SPECIFICATION FOR THE INVENTION ENTITLED:

"A GUARDED POWER CIRCULAR SAW ASSEMBLY"

This invention is described in the following statement:-

## BACKGROUND TO THE INVENTION

This invention relates to power circular saws and in particular to power circular saws that are pivotally moveable with respect to a base or work piece support surface. These types of saws are sometimes referred to as "drop saws".

5

The following discussion providing some background to the invention is intended to facilitate a better understanding of the invention. However, it should be appreciated that the discussion is not an acknowledgement or admission that any of the material referred to was published, known or part of the common general  
10 knowledge in Australia as at the priority date of the application.

Conventional drop saws provide little, or no protection to the operator from injury by the cutting blade. While drop saws are often equipped with blade guards, these guards generally retract progressively as the saw is lowered towards the base  
15 or work piece support surface. Exposure of the cutting blade makes it possible for the operator to inadvertently place his hands or fingers in the path of the saw.

It is an object of the invention to provide a guarded power circular saw assembly that reduces the likelihood of injury to the operator. More particularly, it is  
20 an object of the invention to keep the blade fully guarded during cutting operations.

## SUMMARY OF THE INVENTION

According to the invention there is provided a guarded power saw assembly comprising;

25

a base for supporting a work piece;

— a circular saw blade;

a drive motor operatively connected to the saw blade;

a head supporting both the drive motor and the saw blade, with the head mounted to the base for movement through an arc about a primary pivot axis from a  
30 raised position above the base to a lowered position engaging the base;

an arm having a proximal end and a distal end, the proximal end mounted to the head for movement through an arc about a secondary pivot axis and the distal end supporting the circular saw blade;

5 a first locking means operatively interposed between the head and arm, the locking means having a locked condition in which the arm is locked to the head so as to keep the saw blade enclosed by the head and an unlocked position in which the arm is pivotally movable with respect to the head to allow a portion of the blade to exit the head; and

10 a handle extending from the head and operatively connected to the arm, wherein the handle is movable to first rotate the locked together head and arm with respect to the base towards the work piece and, after the head has engaged the base, to then pivot the arm with respect to the head such that the saw blade exits the head to cut the work piece.

15 The saw blade is always positioned out of reach of the operator so as to eliminate, or at least reduce, the possibility of injury. Initially the saw blade is enclosed within the head in its raised position. Unlike other drop saws, there is no progressive exposure of the blade as the head is lowered towards the work piece. It is not until the head engages the base that the locking means is released to allow the  
20 arm, and hence the blade, to be lowered with respect to the head. With the head engaged with the base, it is not possible for the operator to place his hands or fingers in the path of the blade.

Preferably the assembly further comprises:

25 a second locking means operatively interposed between the head and the base, the second locking means having an unlocked condition in which the head is pivotally movable with respect to the base and having a locked condition in which the head is locked to the base after the head has engaged the base and the arm has commenced rotation with respect to the head.

30

Thus after the blade has exited the head, the head is locked to the base thereby preventing access to the blade during cutting.

Preferably the first locking means comprises:

a first latch member mounted to the arm;

a second latch member mounted to the head for movement with respect to the head and co-operable with the first latch member,

5 whereby the locking means is unlocked by movement of the second latch member as it engages a base-dependent member when the head engages the base.

Preferably the first latch member comprises a pin and the second latch member comprises a pivotally mounted latch arm, the latch arm having a recess

10 shaped and positioned to lockably receive the pin.

Preferably the latch arm is biased to engage the recess against the pin.

Preferably the primary and secondary pivot axes are parallel and spaced

15 apart.

Preferably the second locking means comprises:

a wall depending from the arm or handle;

a projection extending from the base,

20 wherein the projection and wall are co-operably arranged to prevent, or substantially limit, movement of the wall about the primary pivot axis, thereby preventing, or substantially limiting, movement of the head with respect to the base, after the head has engaged the base and the arm has commenced rotation with respect to the head about the secondary pivot axis.

25

Preferably the wall is arcuate having a center of radius coincident lying on or adjacent to the secondary pivot axis.

Preferably the head has a removable cover shaped to guard the blade. The

30 removable cover allows access to the blade for inspection or replacement.

Preferably the base includes a U-shaped channel, longitudinally disposed perpendicular to the plane of the blade, for receiving the work piece. A second U-shaped channel orientated at 45° to the aforementioned U-shaped channel is provided to allow for 45° mitre cuts.

5

Preferably the assembly includes a work piece and off-cut clamp assembly.

Preferably, after initial pre-adjustment of the clamp assembly, the clamp assembly is automatically actuated as the head is lowered towards the work piece.

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Specific embodiments of the invention will now be described in some further detail with reference to and as illustrated in the accompanying figures. These embodiments are illustrative, and are not meant to be restrictive of the scope of the invention.

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#### DETAILED DESCRIPTION OF A PREFERRED EMBODIMENT OF THE INVENTION

A preferred embodiment of the invention is illustrated in the accompanying figures in which:

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Fig 1 shows a perspective view of a guarded power circular saw assembly according to a first embodiment of the invention with its head up and the blade still in its raised position.

Fig 2 shows the saw of Fig 1 from underneath.

25

Figs 3 and 4 show the saw of Fig 1 with its head being progressively lowered to the fully lowered position shown in Fig 4.

Fig 5 shows the saw of Fig 1 with its blade cover removed to show the cutting blade.

30

Figs 6 and 7 show a detailed perspective view of a first locking means for locking the movement of the drive arm with respect to the head. These Figs show the first locking means in a fully locked condition.

Figs 8 and 9 show the first locking means of Figs 6 and 7 in a partially locked condition.

Figs 10 to 13 show components of the saw assembly of Fig 1 in a partial cutaway cross-sectional view with the arm and head moving from a fully raised to a fully lowered position. These Figs show the progressive action of a second locking means.

5        Fig 14 shows a perspective view of a guarded power circular saw assembly according to a second embodiment of the invention with its head down but the blade still in its raised position.

      Fig 15 shows the saw assembly of Fig 14 in the same configuration but with the blade cover removed.

10       Fig 16 shows a sectional view of the saw assembly of Figs 14 and 15 with the head raised ready for loading a work piece.

      Fig 17 is a view of the saw assembly similar to Fig 16 but with the head lowered and the blade ready to cut.

      Fig 18 is a similar view to that of Fig 17 but with the head and blade lowered.

15       Fig 19 is a similar view to that of Fig 15 enlarged with the drive arm belt cover removed showing the blade drive train and spindle lock.

      Fig 20 is a longitudinal section of the saw assembly of Figs 14 to 19 showing the blade cover still fitted and the spindle lock disengaged.

20       Referring to Fig 1, a guarded power circular saw 10 according to a first embodiment of the invention has a base 30 with a channel 32 for receiving a work piece extending therethrough and a head 20 for supporting the drive motor and the saw blade. The head 20 is mounted to base 30 for movement through an arc about a primary axis 22 (shown in Fig 10) from a raised position above the base 30 to a  
25       lowered position engaging the base 30.

      The drive motor is housed within motor housing 42. A single handle 40 is provided for performing the functions of lowering the head 20 while semi-automatically applying a clamp to the work piece and rotating the saw out from the  
30       head to cut the work piece.

The head 20 includes a removable cover 28 to allow access and replacement of the saw blade 58 as shown in Fig 5.

Referring to Fig 4, the head 20 is shown in its down (lowered) position with its base plate 26 in contact with the base 30. Fig 5 shows that handle 40 is operatively connected to a drive arm 50 by a spigot that extends from the drive motor housing 42 and these two components are pivotally mounted to the head base plate 26 by arm pivot bracket 44 for rotation about a secondary point axis 45 (best shown in Figs 12 and 13). A drive arm return spring 49 is provided to bias the drive arm upwards.

From the position shown in Figs 4 and 5, an operator can further rotate handle 40 towards the work piece within channel 32 to rotate arm 50 and hence blade 58 out through slot 27 within head base plate 26 to engage and cut the work piece.

Referring to Fig 1, the saw assembly is shown in its at rest position with head raised. In this position channel 32 is exposed ready to receive a work piece. In this position the saw blade 58 cannot exit the head 20. More specifically the blade 58 cannot move out through the head base plate 26 through slot 27 (shown in Fig 5).

The mechanism for preventing the blade 58 moving prematurely with respect to the head 20 is as follows. Blade 58 is mounted on drive arm 50. A first latch member in the form of a retaining pin 53 extends from drive arm 50 (as shown in Fig 7) to form part of a first locking means operatively interposed between the head 20 and the arm 50. The first locking means includes a primary latch arm 52b mounted to the head base plate 26 by a pivot 55 (refer Figs 6 & 7). Latch arm 52b has a notch 59 (shown in Fig 9) that engages retaining pin 53 to lock the head 20 to the arm 50. A latch arm release pin 54 is mounted to the base 30 as shown in Fig 3. Once the head 20 has been lowered onto the base 32 by the operator depressing handle 40 as shown in Fig 4, the latch arm release pin 54 holds an end of the latch arm 52b up against return spring 51. In this position, the latch arm 52b is slightly rotated about pivot 55 such that notch 59 releases pin 53 so that further movement of handle 40 downwards towards the base 30 causes arm 50 and therefore blade 58 to exit the head 20 through



slot 27 within base plate 26 towards the work piece as is progressively shown by Figs 12 and then 13.

The first locking means operatively interposed between the head 20 and the arm 50, described above, ensures that the blade 58 cannot exit the head 20 until the head base plate 26 has closed over the base 30. This ensures that the operator cannot inadvertently bring the blade into contact with the operators hands or fingers. While the locking means described above incorporates a latch arm 52b mounted to the head base plate 26 by a pivot mount 55, other locking means may be used.

The first locking means described so far will not prevent an operator raising the head 20 after the head 20 has engaged the base 30 and the blade 58 has exited the head. It is possible that an operator may attempt to lift the head 20 during cutting of a work piece. In order to prevent this, a second locking means is provided.

The second locking means is best shown in Figs 10 through to 13. The second locking means is operatively interposed between the head 20 and the base 30. The second locking means comprises an arcuate wall 102 depending from the arm 50 and a projection in the form of a pin 104 extending from the base 30. The pin 104 and wall 102 are co-operably arranged to prevent raising of the head 20 during the cut. This co-operable arrangement is such that movement of the wall 102 about the primary pivot axis 22 cannot occur after the head is engaged the base 30 and the arm 50 has commenced rotation with respect to the head about the secondary pivot axis 45. This is clearly evidence in Fig 13 which shows that if an attempt is made to lift the head 20, the arcuate wall 102 will foul the pin 104 because of the relative positioning of the primary axis 22 and the secondary axis 45.

With the locking arrangements described thus far, there is a small angular delay during which the primary locking means has unlocked and before the secondary locking means has locked. In order to enable the movement of the head 20 with respect to the base 30 from the position shown in Fig 11 to the position shown in Fig 12, it is necessary to provide clearance between the end of 103 of the arcuate wall

102 and the pin 104. Referring now to Fig 12, it can be seen that because of this clearance, movement of the arcuate wall with respect to the primary pivot axis 22 is not restrained during initial movement of the arm 50 downwards towards the base 30. Thus, with the first locking means unlocked (since primary latch arm 52b has moved into the position shown in Fig 9 freeing pin 53 from recess 59b). In order to prevent the head 20 being lifted with respect to the base 30 during this delay period, a secondary latch arm 52a is provided as shown in Figs 7 to 9.

If the head 20 is manually lifted away from the base 30 during the delay period and before the secondary locking means is operative, the secondary latch arm 52a will return to the locked position shown in Fig 9. It is able to return to its locked position because of the extra length of the recess 59a (as compared to recess 59b). This movement of the secondary latch arm 52a is caused by spring 51a as soon as the head is lifted a small amount away from arm lock release pin 54 mounted to the base 30 as shown in Fig 8. As a result, exposure of the blade 58 is not possible even though the primary latch 52b is not effective once relative movement has occurred between the arm 50 and the head 20.

The saw assembly 10 as described above can be used to cut various materials with the correct selection of saw blade 58. It is envisaged that the saw assembly 10 will be particularly appropriate for cutting steel. When cutting steel with a conventional circular saw the operator faces the hazard of small sharp steel cuttings (or swarf) travelling at high velocity from the region of the blade. However with the above described saw assembly 10, the blade is sufficiently enclosed to prevent swarf escaping.

When sawing a work piece, it is generally desirable to have the work piece firmly clamped to a support base. This is particularly the case when cutting steel as the effect of an unclamped work piece twisting during cutting can be serious in terms of blade damage. Therefore in the above described first embodiment of the invention there is provided a pair of clamps 80 (shown in Fig 5) which semi-automatically clamp the work piece in position within channel 32 as the head 20 is lowered.

A semi-automatic clamping system is illustrated in Figs 1 and 2. This system allows for multiple cutting of the same cross-section work piece without any clamp adjustment required, once the clamps have been pre-adjusted for that particular cross-section.

Two identical clamp mechanisms are employed. One is provided for the work piece and the other is provided for the off-cut. Each has an identical interlock assembly.

Again, referring to Figs 1 and 2, each clamp 80 comprises a clamp body and an adjustment knob 81. The adjustment knobs 81 allow loosening of the clamp bodies 82 so that they can be pushed against the work piece in an initial position. This initial position, which can allow up to 1mm of clearance can then be locked by tightening knobs 81.

An eccentric crank 85 mounted around the head/pivot, together with a link 83 connected to the clamp body 82 as shown in Fig 2 is provided to facilitate automatic clamping. The link 83 is made up of two halves 83a and 83b which are joined by a compression spring 86. The spring 86 provides the "give" allowing full movement of the head 20 and the eccentric crank 85 to go "over centre" to lock the clamps 80 without the clamp force operating to raise the head again.

Interlocks are provided to prevent the cut proceeding (with possible blade damage) if the clamps 80 are not adequately pre-adjusted. The interlocking arrangement is shown in Figs 2 and 3. When a work piece is adequately clamped, a compression spring 86 between the link halves 83a and 83b undergo significant compression and therefore, the link 83a moves only a small distance. Alternatively, if the work piece is not adequately clamped, link half 83a will move a significant distance before compression of the spring 86 occurs.

Again, referring to Fig 2, it can be seen that linear movement of the link 83a will result in rotary movement of cam 87. When the clamp 80 is in the release position, pin 88, which is spring loaded upwards and shown in Fig 2 in a pushed down state, is free to be pushed down. If the link 83a moves forward to a significant extent, cam 87 will rotate to a position which prevents the descent of pin 88. As explained above, link 83a will move forward a significant amount only when the work piece is not adequately clamped due to failure to correctly pre-adjust the clamp position.

If pin 88 is locked up by cam 87, the projecting pins 88, as shown in Fig 1, prevent the head from being fully lowered, thus preventing the cut from proceeding. This configuration is illustrated in Fig 3 in which it can be clearly seen that pins 88 are preventing the further lowering of the head baseplate 26. In contrast, the fully lowered position, only achievable when a work piece has been adequately clamped, is illustrated in Fig 4.

In the event that only one clamp 80 can be used, for instance when trimming a short off-cut from a work piece, the clamp 80 on the off-cut side is adjusted to abut the rear face of the trough instead of the work piece. This will satisfy the interlock conditions and has the added advantage of closing a potential swarf leakage path.

The pair of clamps 80, positioned either side of the blade 58, ensure that both the work piece and off-cut are securely held during cutting and until the saw blade 58 is retracted. The clamp 80 on the off-cut side has two parallel spaced-apart blades. The first of these blades is positioned close to the saw blade 58 and the second is further along the channel 32 as shown clearly in Fig 1. This enables both small and large off-cut pieces to be securely held during and immediately after cutting.

Referring to Fig 14 a guarded power circular saw 10 according to a second embodiment of the invention has a base 30 with a channel 32 for receiving a work piece extending therethrough and a head 20 for supporting the drive motor and the saw blade. The drive motor is housed within motor housing 42. A single handle 40 is

provided for performing the functions of lowering the head while automatically applying a clamp to the work piece and rotating the saw out from the head to cut the work piece.

- 5           The head 20 includes a removable cover 28 to allow access and replacement of the saw blade 58 as shown in Fig 15.

Referring to Fig 15, the head 20 is shown in its down (lowered) position with its base plate 26 in contact with the base 30. Handle 40 is operatively connected to a  
10   drive arm 50 by a spigot that extends from the drive motor housing 42 and these two components are pivotally mounted to the head base plate 26 by arm pivot bracket 44.

From the position shown in Fig 15, an operator can further rotate handle 40 towards the work piece within channel 32 to rotate arm 50 and hence blade 58 out  
15   through slot 27 within head base plate 26 to engage and cut the work piece.

Referring to Fig 16, the saw assembly is shown in its at rest position with head raised. In this position channel 32 is exposed ready to receive a work piece. In this position the saw blade 58 cannot exit the head 20. More specifically the blade 58  
20   cannot move out through the head base plate 26 through slot 27 (shown in Fig 15). The mechanism for preventing the blade 58 moving with respect to the head 20 is as follows. Blade 58 is mounted on drive arm 50. A arm lock retaining pin 53 extends from drive arm 50 to form part of a locking means operatively interposed between the head 20 and the arm 50. The locking means is in the form of an arm lock 52  
25   mounted to the head base plate 26 by a pivot 55. Arm lock 52 has a notch 59 (shown in Fig 17) that engages retaining pin 53 to lock the head 20 to the arm 50. An arm lock release pin 54 is mounted to the base 30 as shown in Fig 3. Once the head 20 has been lowered onto the base 32 by the operator depressing handle 40 as shown in Fig 17, the arm lock release pin 54 holds an end of the arm lock 52 up against return spring  
30   51. In this position, the arm 52 is slightly rotated about pivot 55 such that notch 59 releases pin 53 so that further movement of handle 40 downwards towards the base 30 causes arm 50 and therefore blade 58 to exit the head 20 through slot 27 within

base plate 26 towards the work piece as is progressively shown by Figs 17 and then 18.

The locking means operatively interposed between the head and the arm, described above, ensures that the blade 58 cannot exit the head 20 until the head base plate 26 has closed over the base 30. This ensures that the operator cannot inadvertently bring the blade into contact with the operators hands or fingers. While the locking means described above incorporates an arm lock 52 mounted to the head base plate 26 by a pivot mount 55, other locking means may be used.

In addition to having a locking means operatively interposed between the head 20 and the arm 50, the saw assembly 10 also has a means for locking the motor drive shaft 60 as shown in Fig 19. The means for locking the drive shaft 60 is, in this embodiment, a drive shaft pinion 62 and a drive shaft lock 70.

Drive shaft lock 70 is best shown in Fig 20. It comprises a pinion stop 72 pivotally mounted at 75 to the head base plate 26. A spring 74 is provided to bias the pinion stop 72 upwards into engagement with the drive shaft pinion 62. In this position the drive shaft 60 cannot rotate and therefore, even if the drive motor is started, the saw will not rotate.

A drive shaft release finger extends from the underside of the head cover 28 (not shown). This finger depresses the drive shaft lock 70 in the region indicated arrow 76 in Fig 20 against the bias of spring 74. Thus, in the position shown in Fig 20, the pinion 62 and hence shaft 60 is free to rotate, but as soon as the head cover 28 is removed from the head, spring 74 lifts pinion stop 72 into engagement with pinion 62 to lock the shaft 60.

The saw assembly 10 as described above can be used to cut various materials with the correct selection of saw blade 58. It is envisaged that the saw assembly 10 will be particularly appropriate for cutting steel. When cutting steel with a conventional circular saw the operator faces the hazard of small sharp steel cuttings

(or swarf) travelling at high velocity from the region of the blade. However with the above described saw assembly 10, the blade is sufficiently enclosed to prevent swarf escaping. Instead the swarf is caught in a sliding draw 90 as shown in Fig 20.

5           When sawing a work piece, it is generally desirable to have the work piece firmly clamped to a support base. This is particularly the case when cutting steel as the effect of an unclamped work piece twisting during cutting can be serious in terms of blade damage. Therefore in the above described embodiment of the invention there is provided a pair of clamps 80 which automatically clamps the work piece in  
10   position within channel 32 as the head 20 is lowered.

          The progressive operation of one of the two clamps 80 can be seen most clearly in Figs 16, 17 and 18. In Fig 16, the head 20 is in its fully raised position and clamp actuating leg 82 is positioned such that both clamp return spring 87 and clamp over  
15   travel springs 88 are in a free substantially uncompressed state. As the head 20 is lowered by pulling on handle 40 the clamp actuating leg 82 rotates thereby pulling clamp rod 85 which produces a force in over travel spring 88 which in turn acts on the inside of the end 89 of the clamp tube 84 to move the clamp tube 84 to the right of  
20   Fig 16 thereby moving clamp 80 in the same direction towards the work piece in channel 32.

          Over travel spring 88 has a relatively high (shift) spring rate compared to that of clamp return spring 87. Therefore, as the head 20 is lowered the clamp return spring 87 is first compressed. Once the work piece is engaged by the clamp 80 the  
25   over travel spring 88 is compressed ensuring a substantial clamping force is applied to the work piece. Because the clamp actuating leg 82 is connected to the head 20 rather than the handle 40, no additional force is applied to the work piece once the head is in its fully lowered position as shown in Fig 17. That is as the handle 40 is lowered from its position shown in Fig 17 to its position shown in Fig 5 no additional  
30   force is applied to the work piece. In other words, full clamping force is applied to the work piece before the blade 58 is released from the head 20.

The pair of clamps 80, positioned either side of the blade 58, ensure that both the work piece and off-cut are securely held during cutting and until the saw blade 58 is retracted. The clamp 80 on the off-cut side has two parallel spaced apart blades. The first of these blades is positioned close to the saw blade 58 and the second is further along the channel 32 as shown clearly in Fig 14. This enables both small and large off-cut pieces to be securely held during and immediately after cutting.

For both of the above-described embodiments, the drive train between blade 58 and the drive shaft 60 is shown most clearly in Fig 19. Drive shaft 60 has a pulley which drives a toothed belt 57. An idler pulley 56 is provided between drive shaft 60 and the mount for blade 58 (not shown). A second toothed belt 57' is provided to transmit power from the idler pulley 56 to the mount for blade 58. Other drive train arrangements may be used. For instance direct drive through gearing may be used.

While the present invention has been described in terms of a preferred embodiment in order to facilitate better understanding of the invention, it should be appreciated that various modifications can be made without departing from the principles of the invention. Therefore, the invention should be understood to include all such modifications within its scope.

Dated this 30<sup>th</sup> day of September 2002.

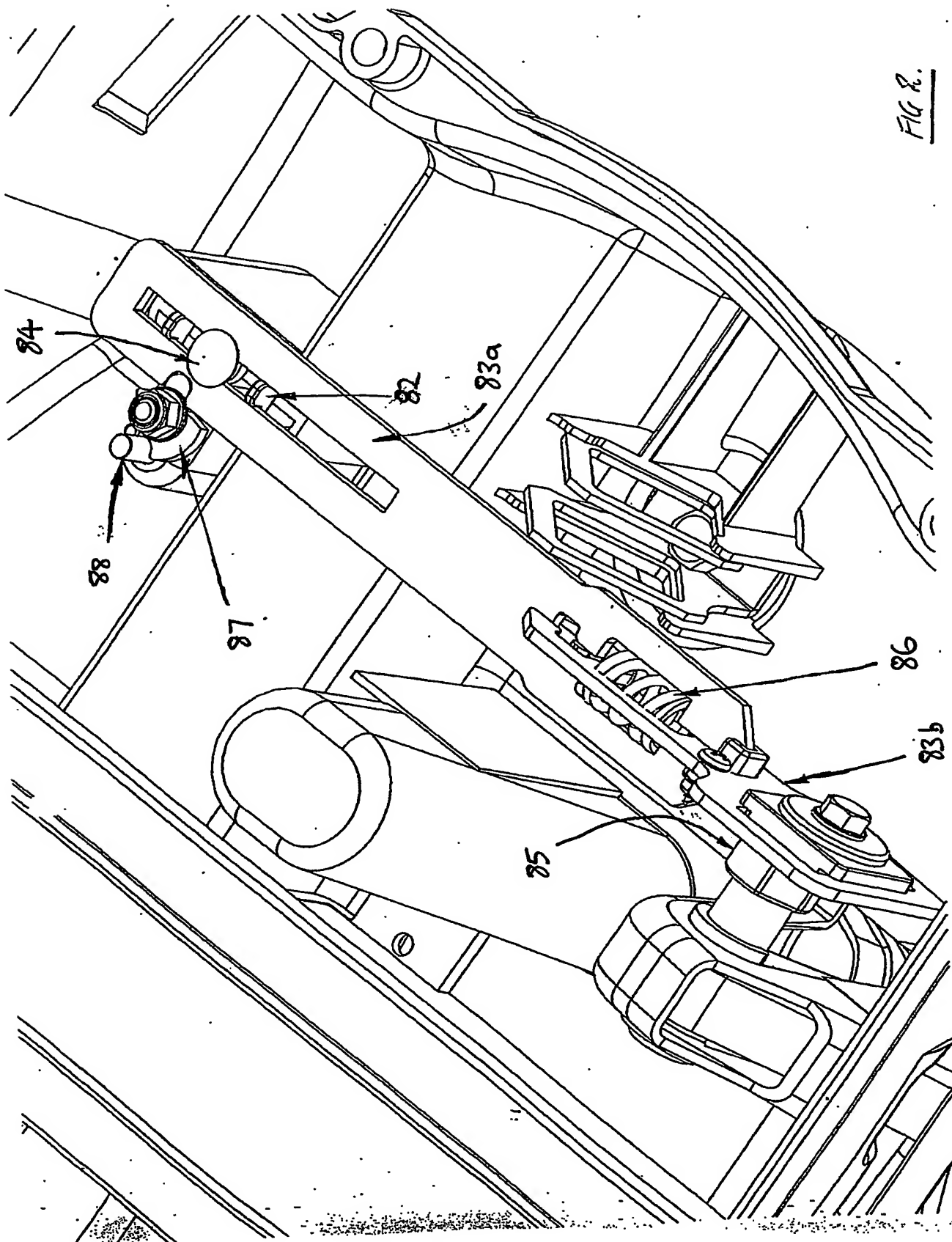
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By its Patent Attorneys  
MADDERNS

*L. A. McNeill*





FIG 8.



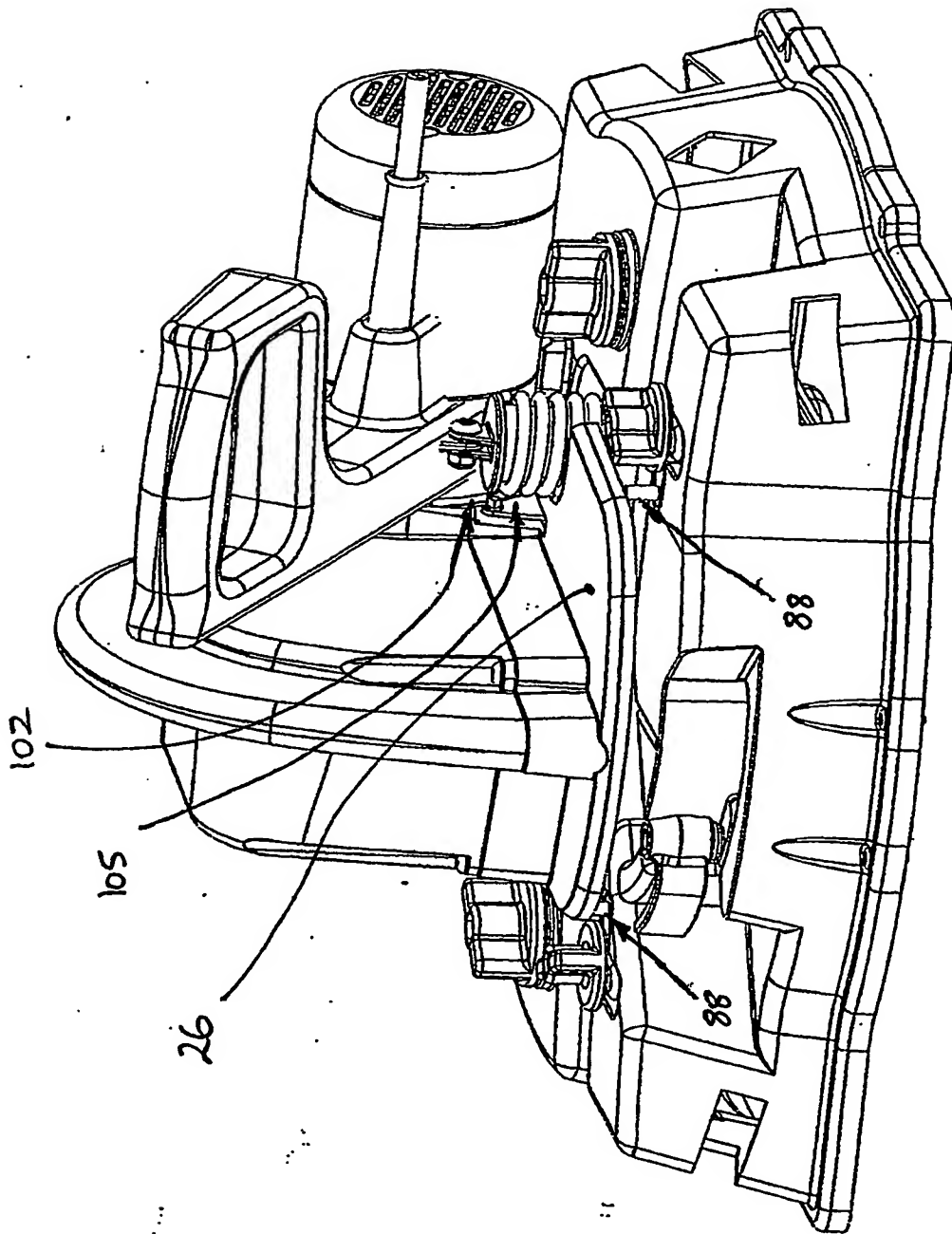


Fig 3.

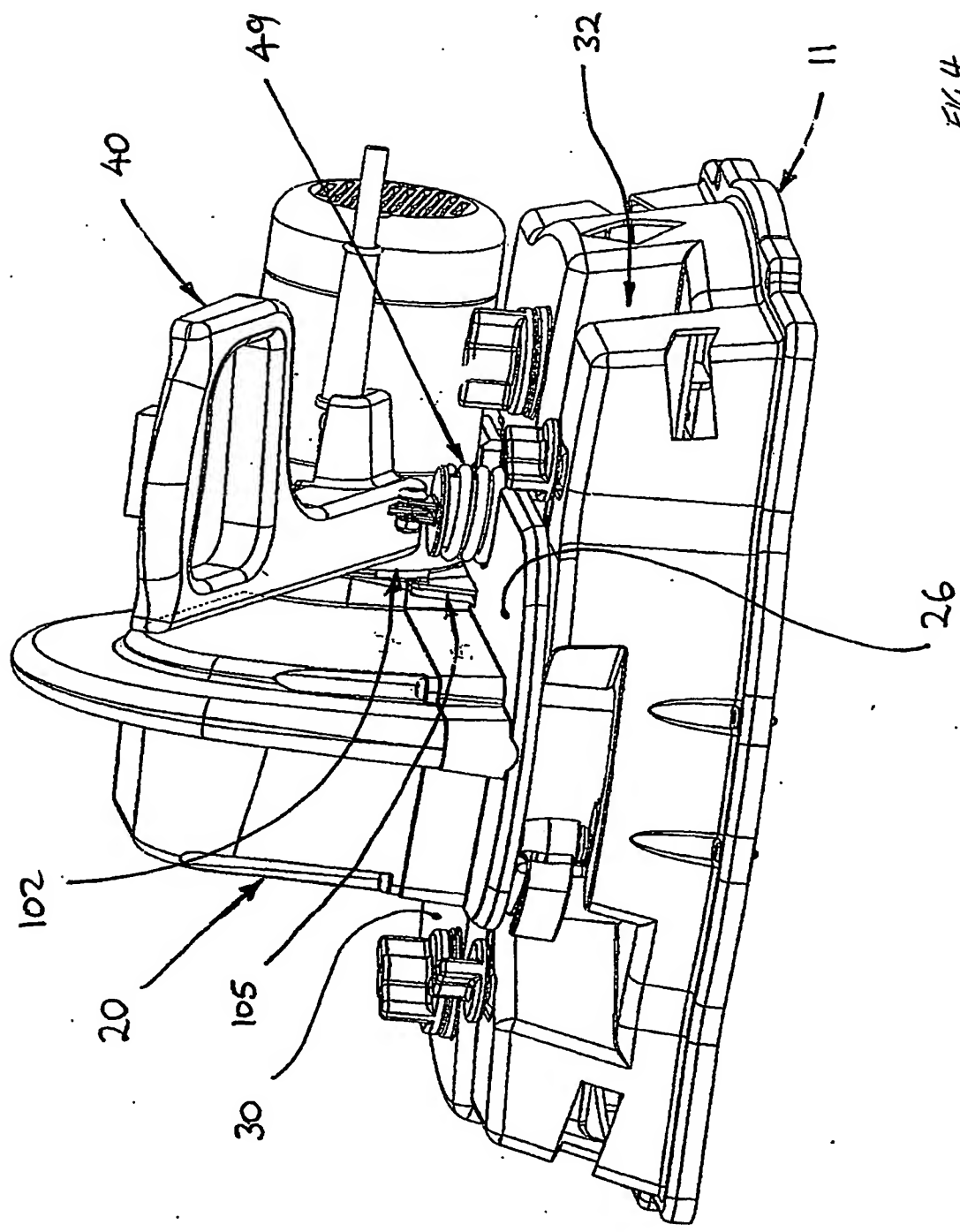


FIG 4.

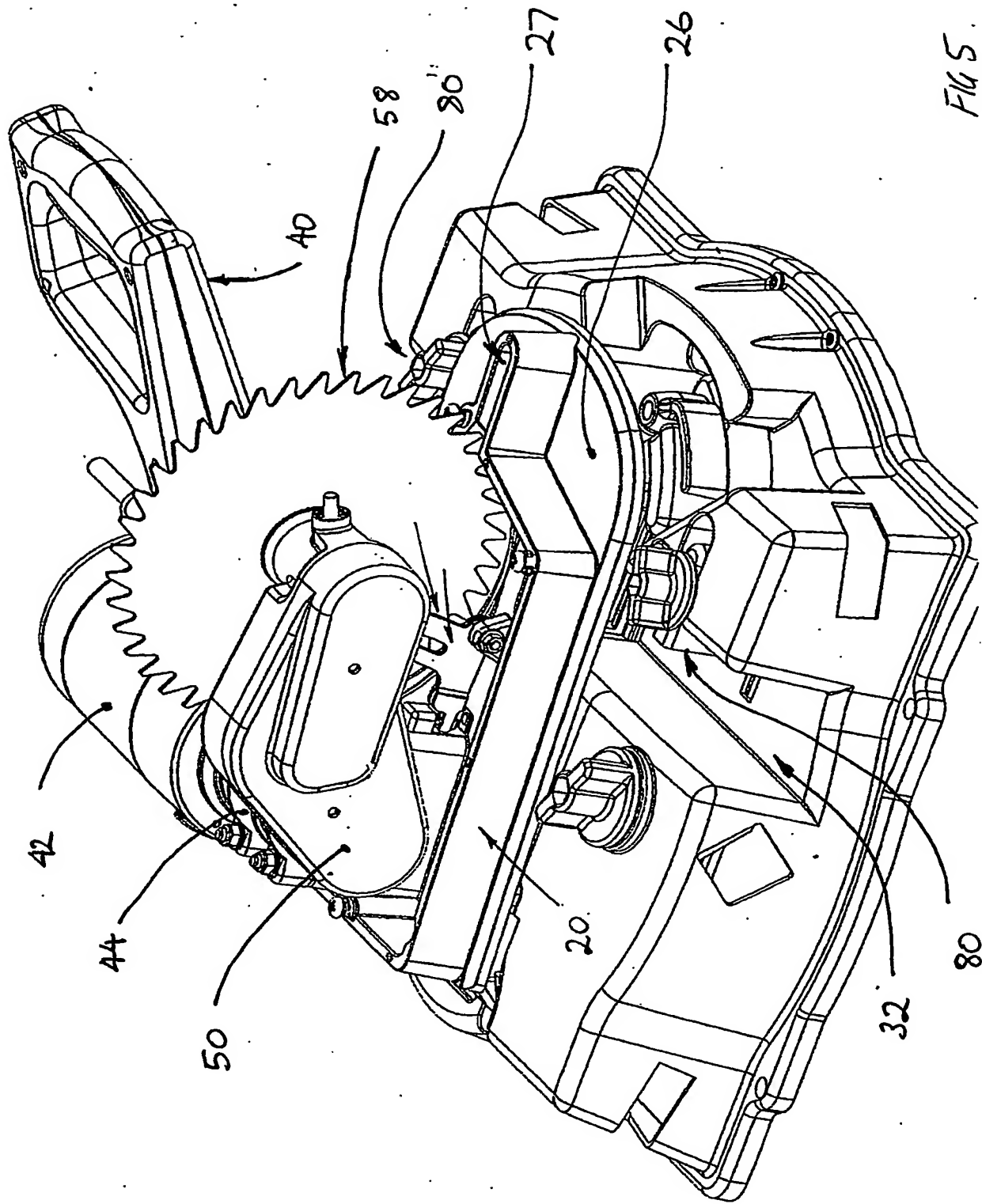


FIG 5

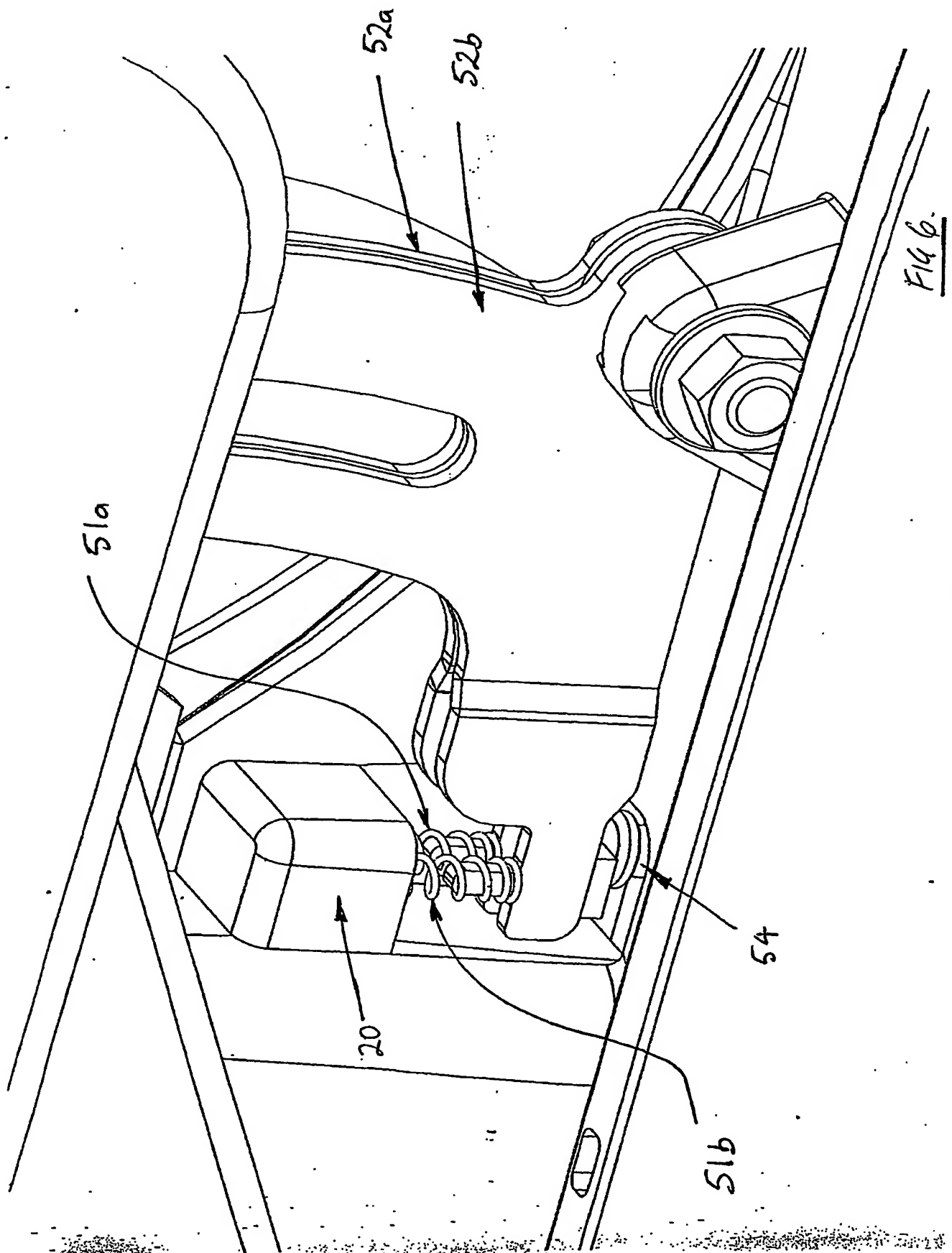
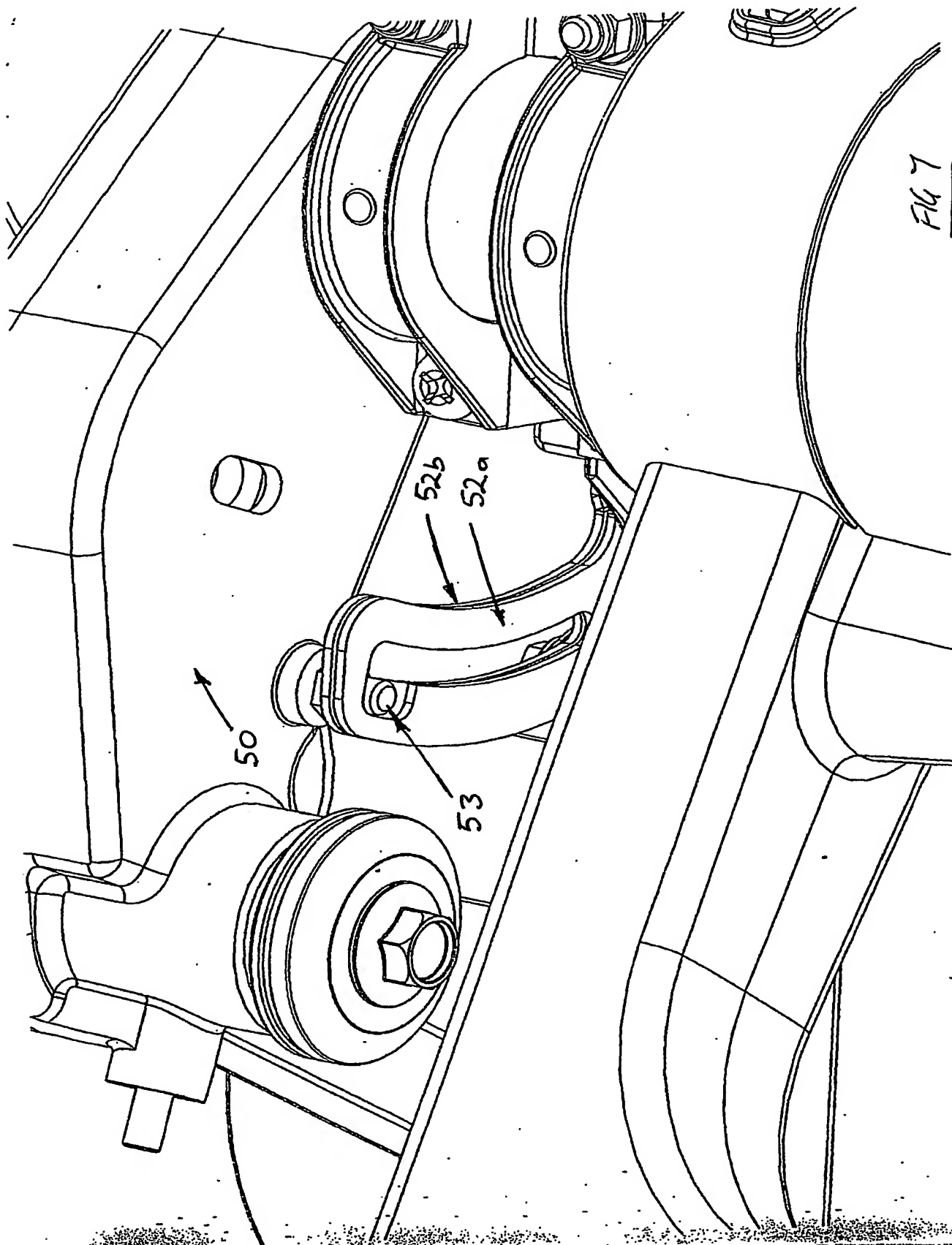


FIG 7



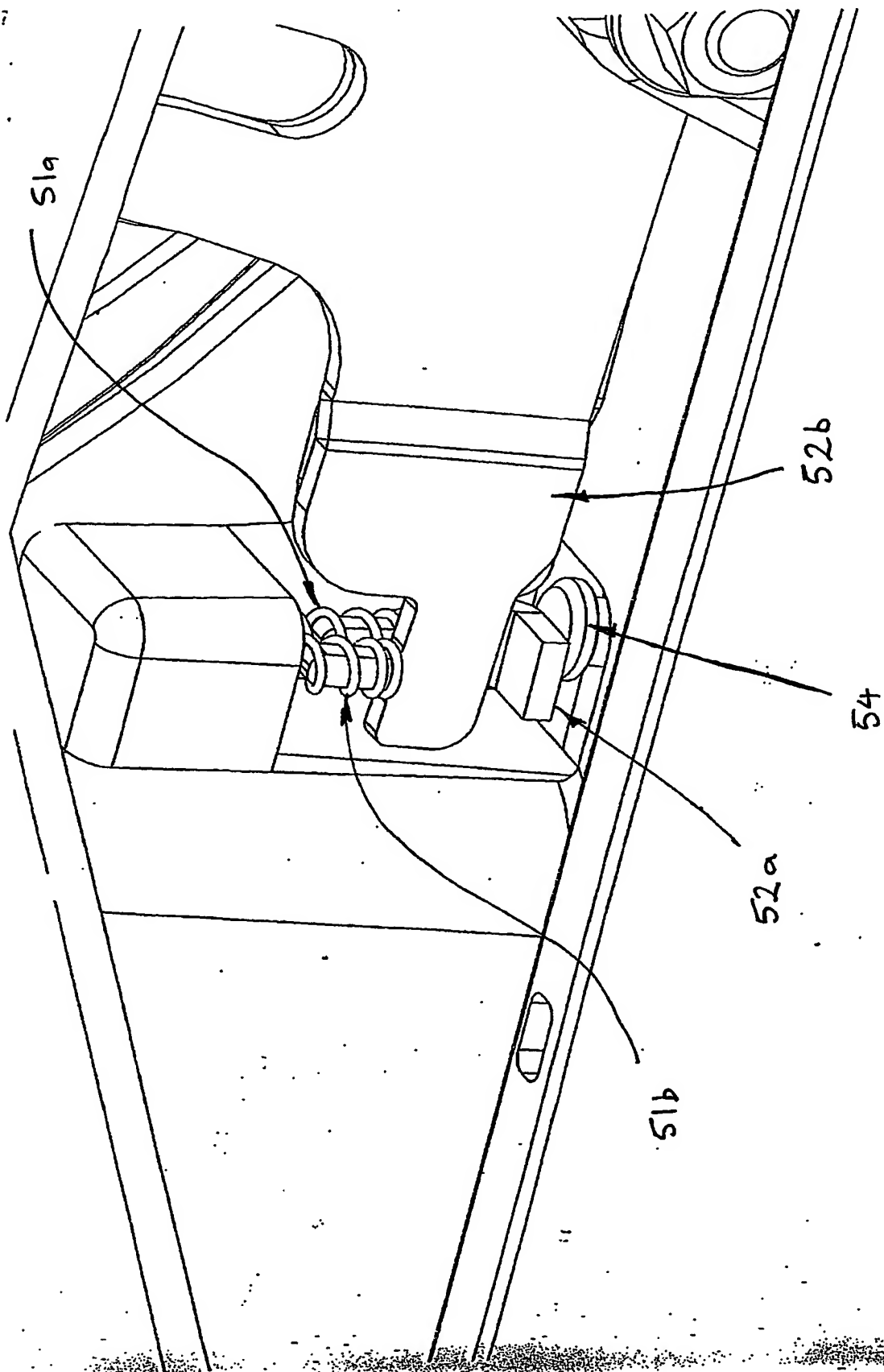
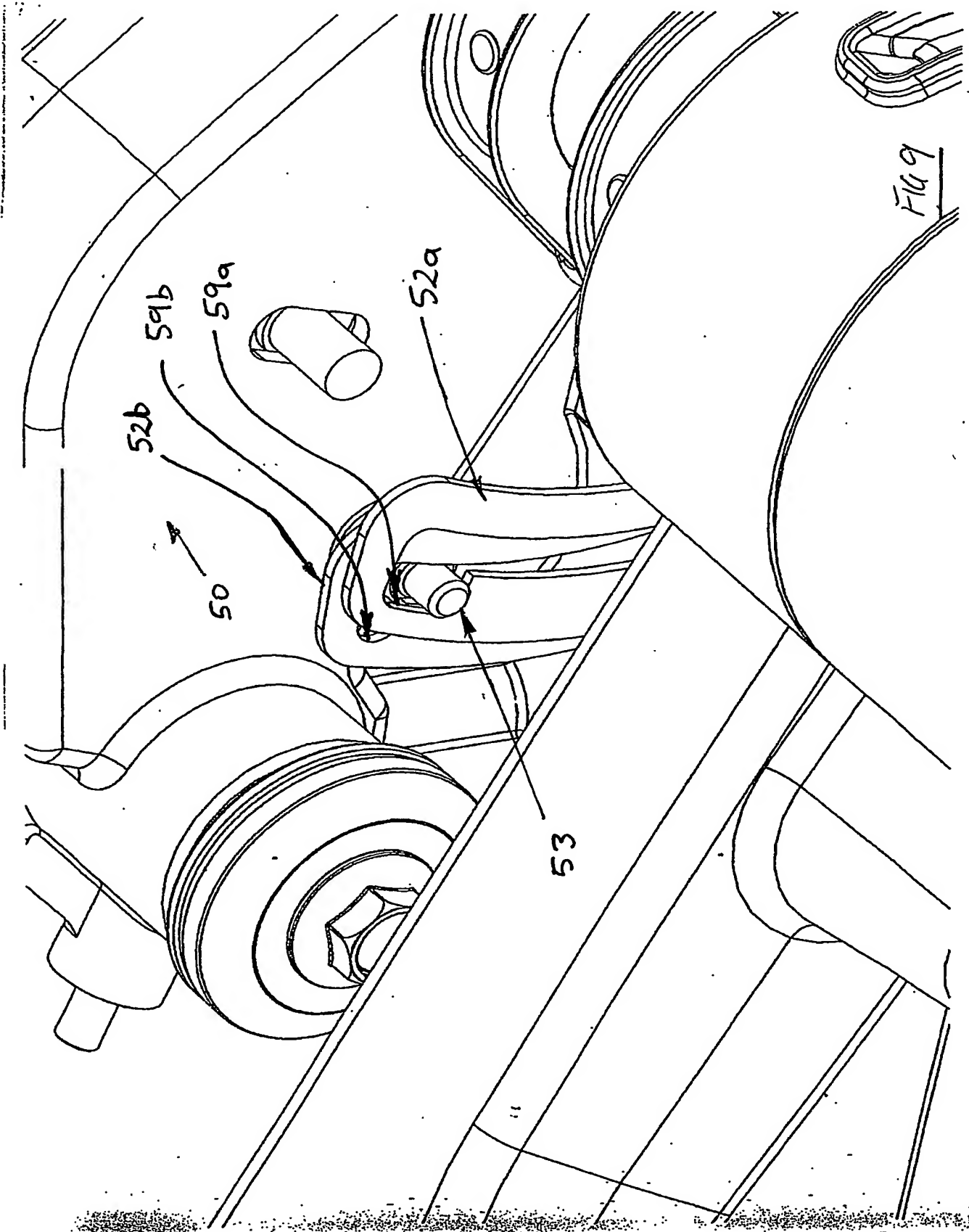


Fig. 8.





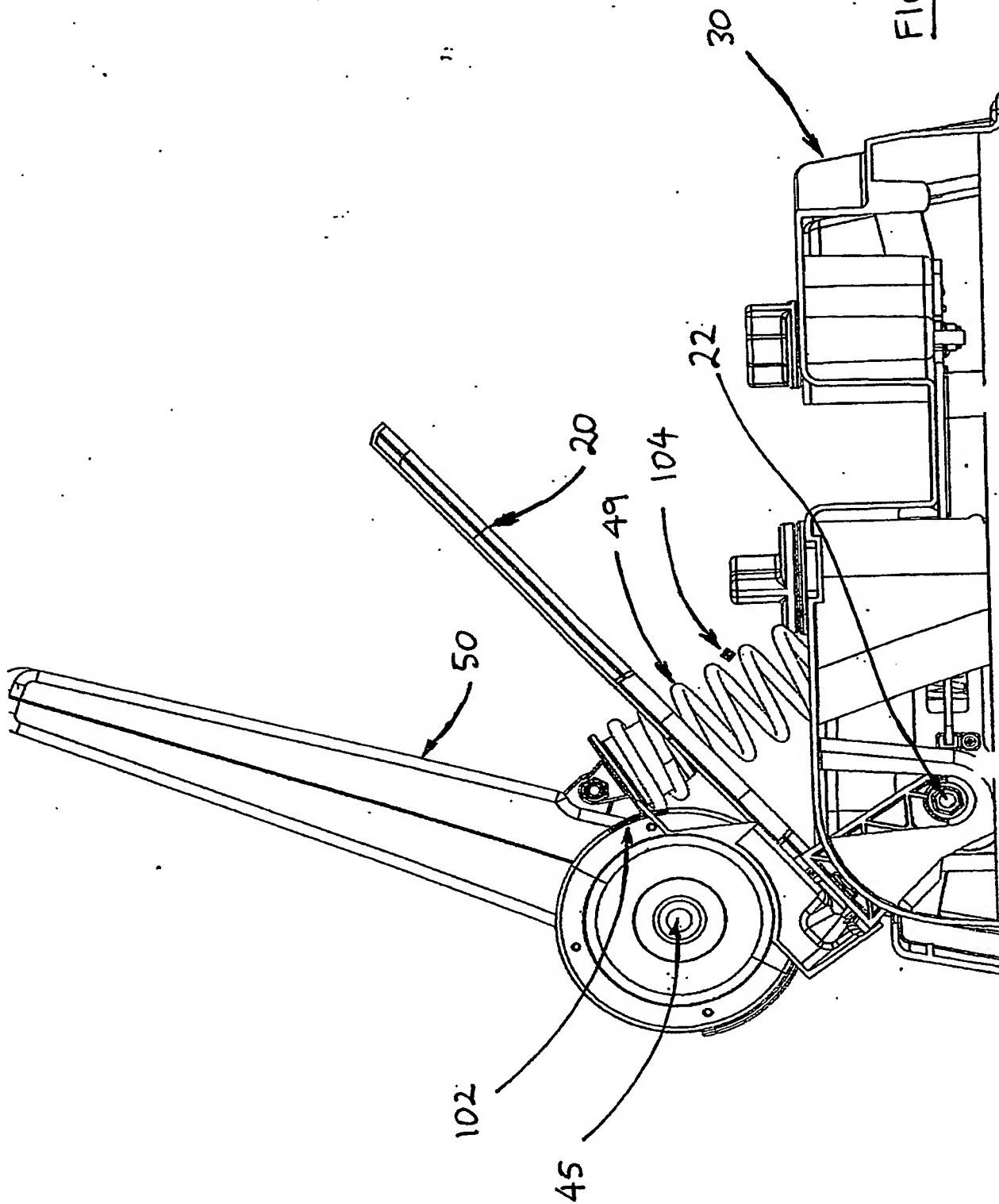
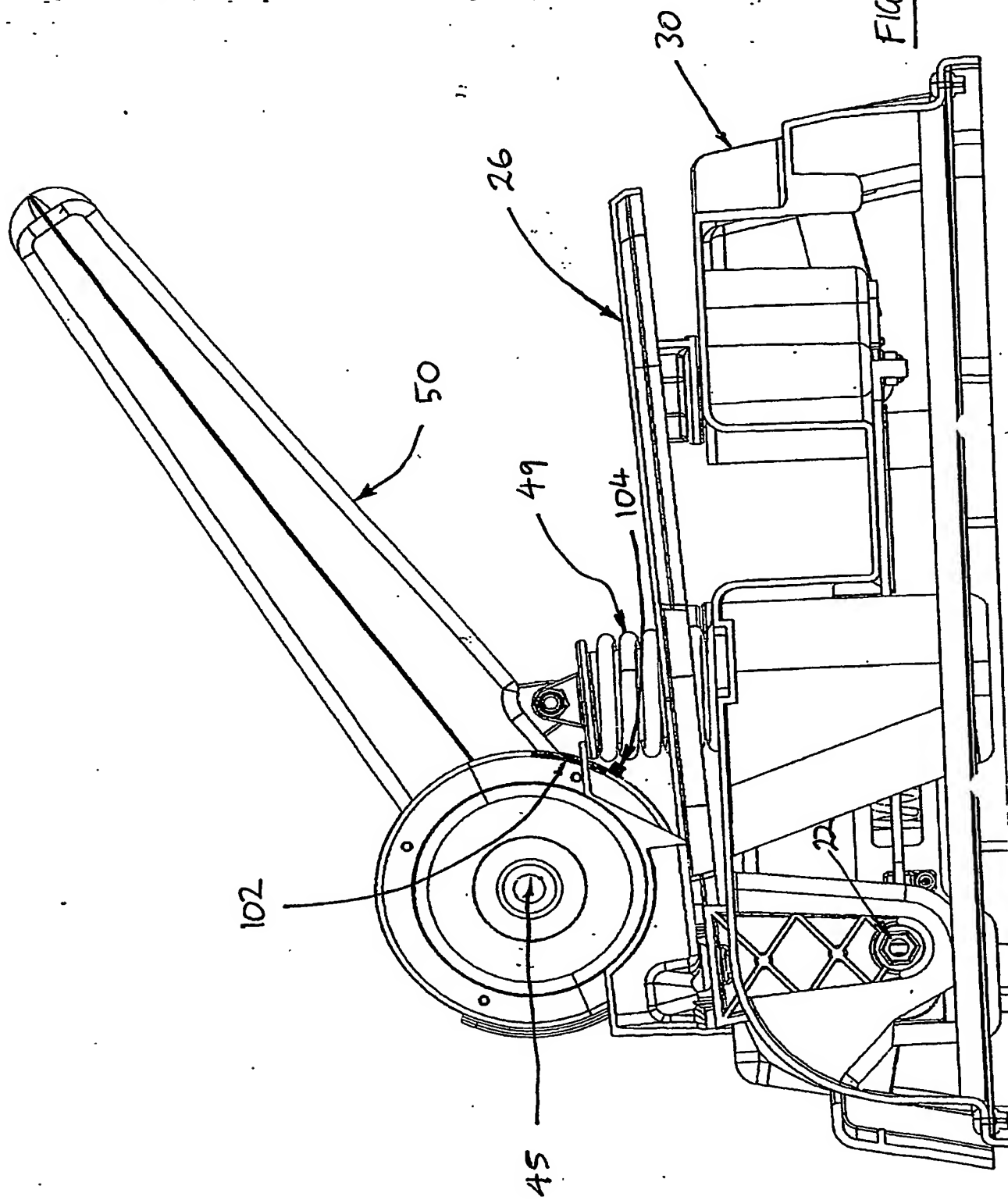


FIG. 10



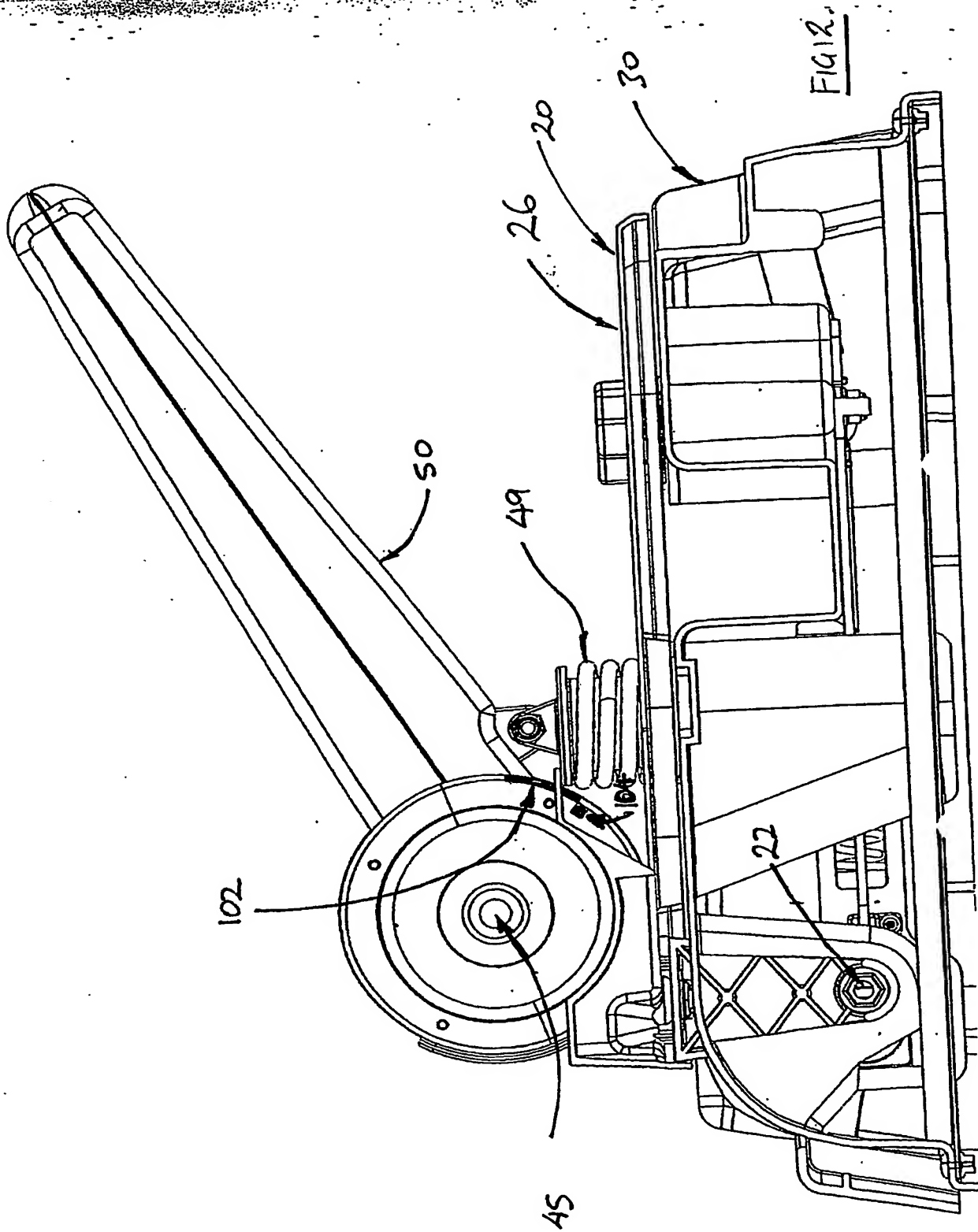


FIG. 12.

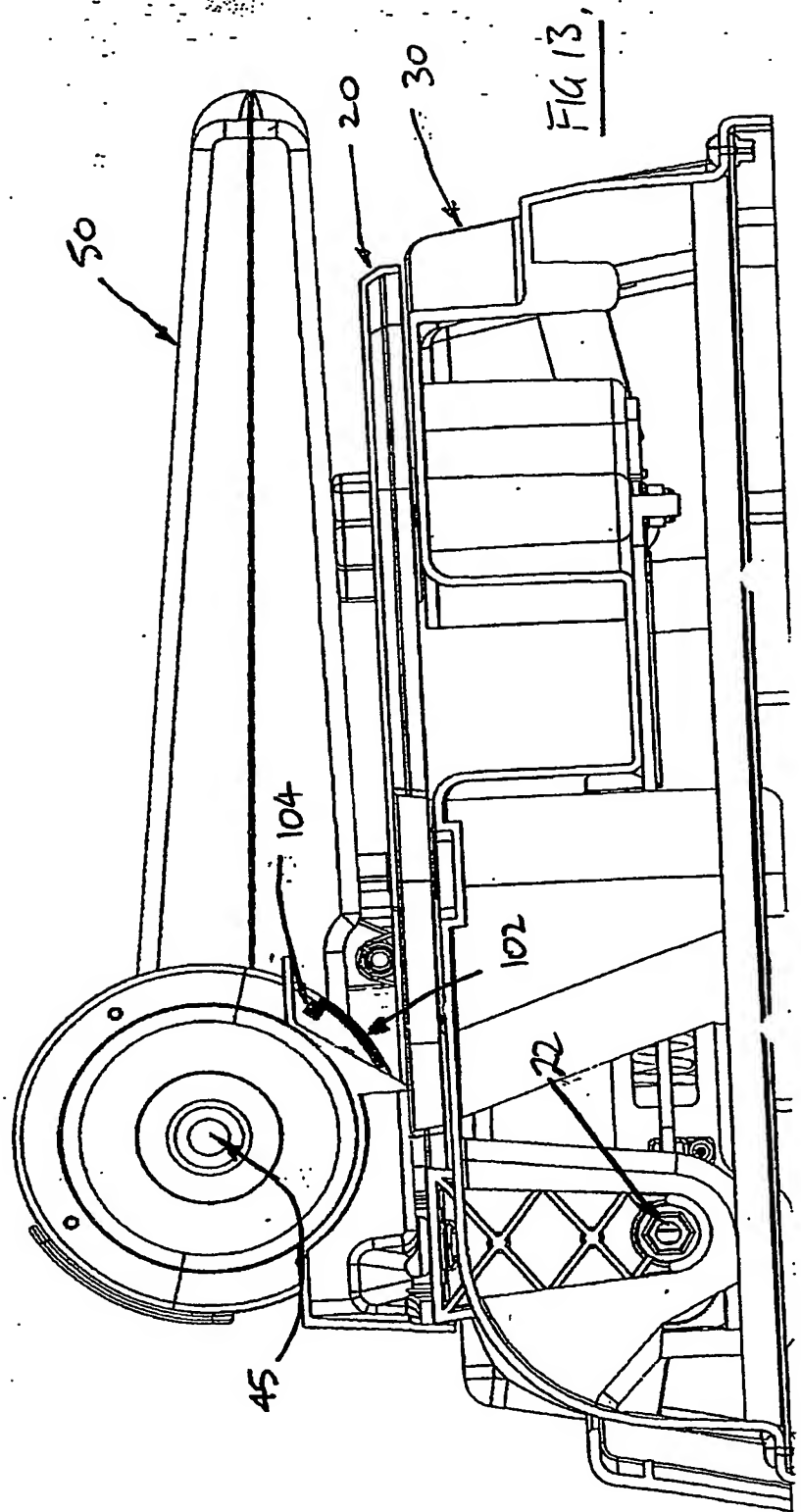


FIG 13,

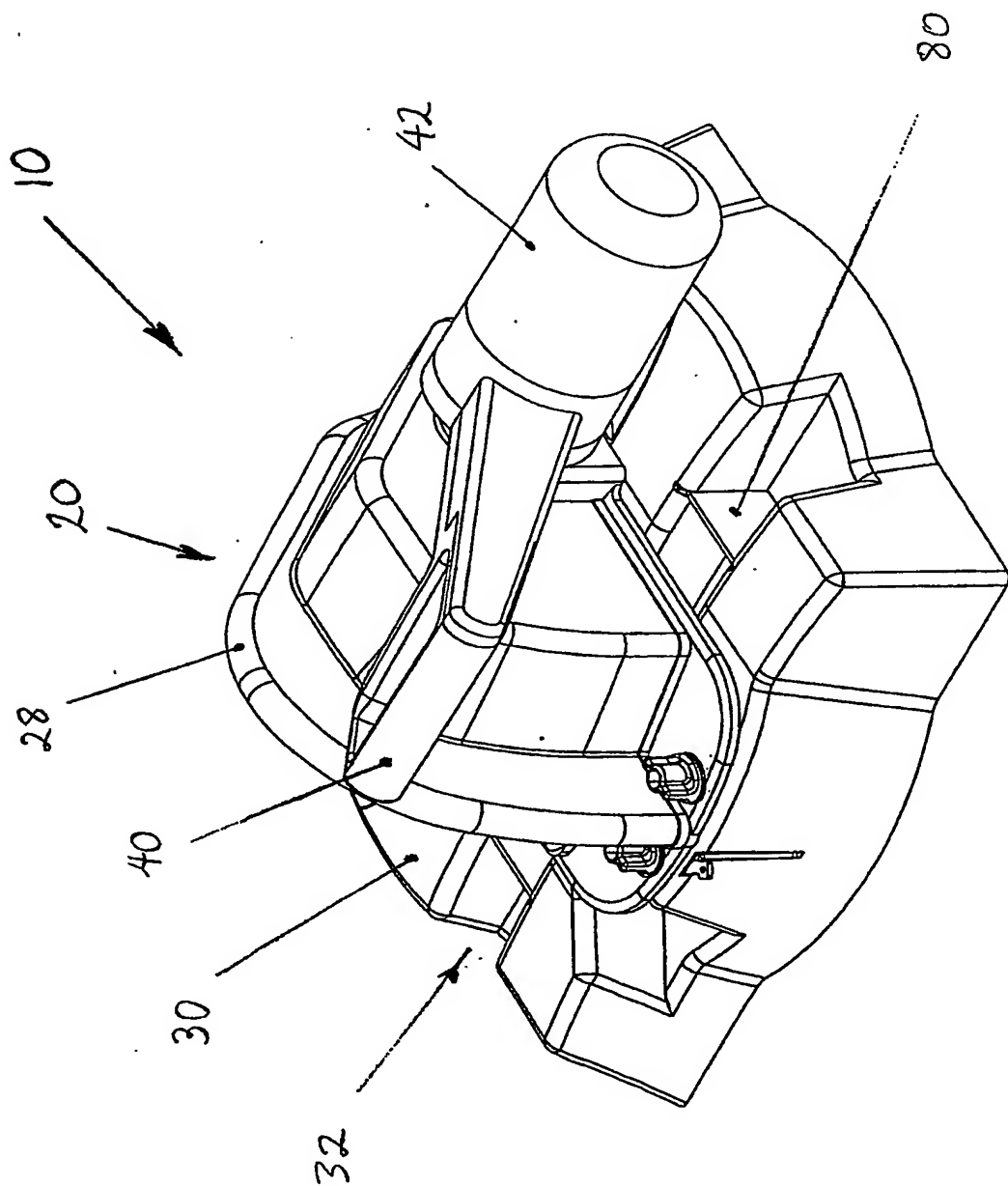


FIG. 14

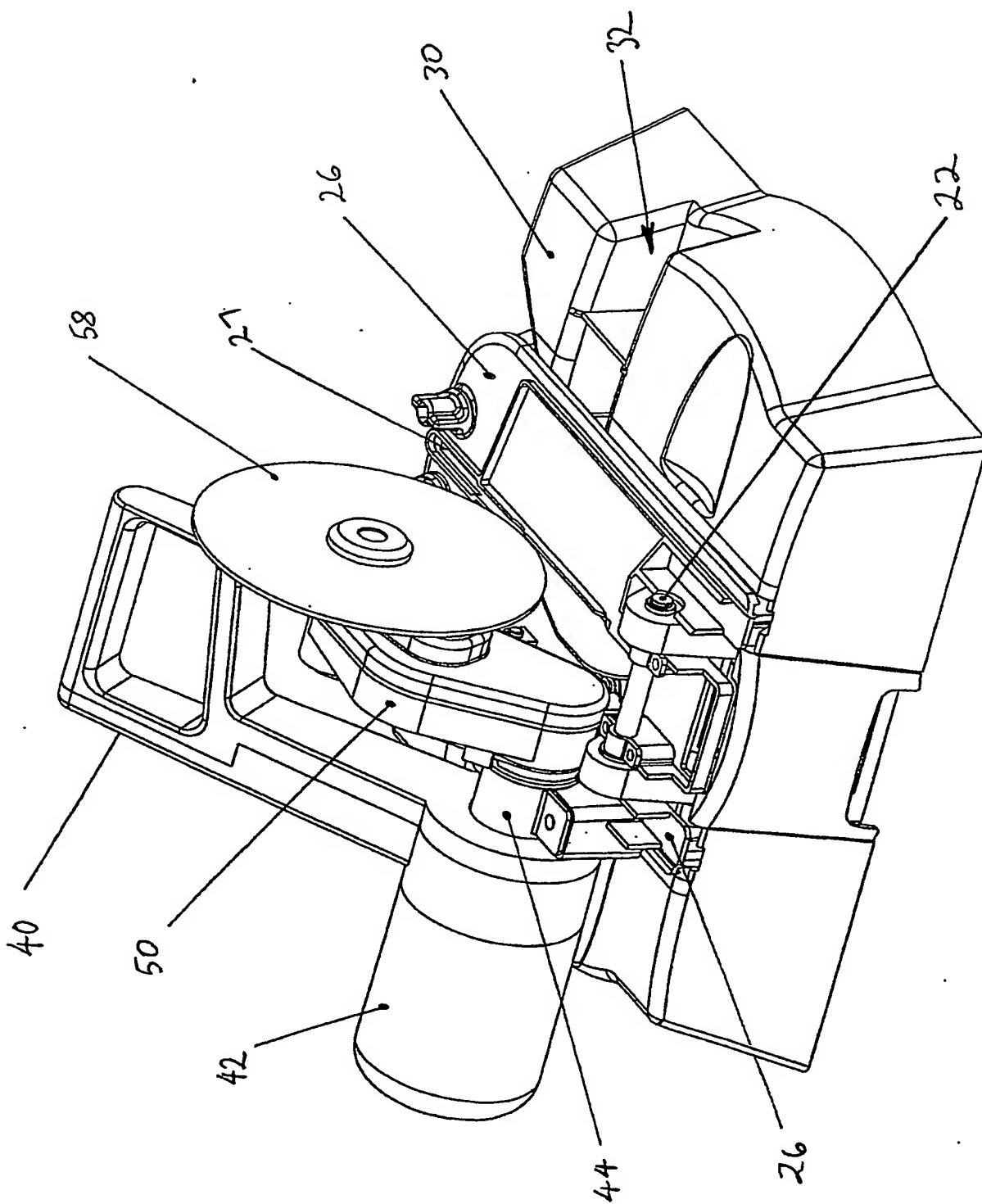


FIG. 15

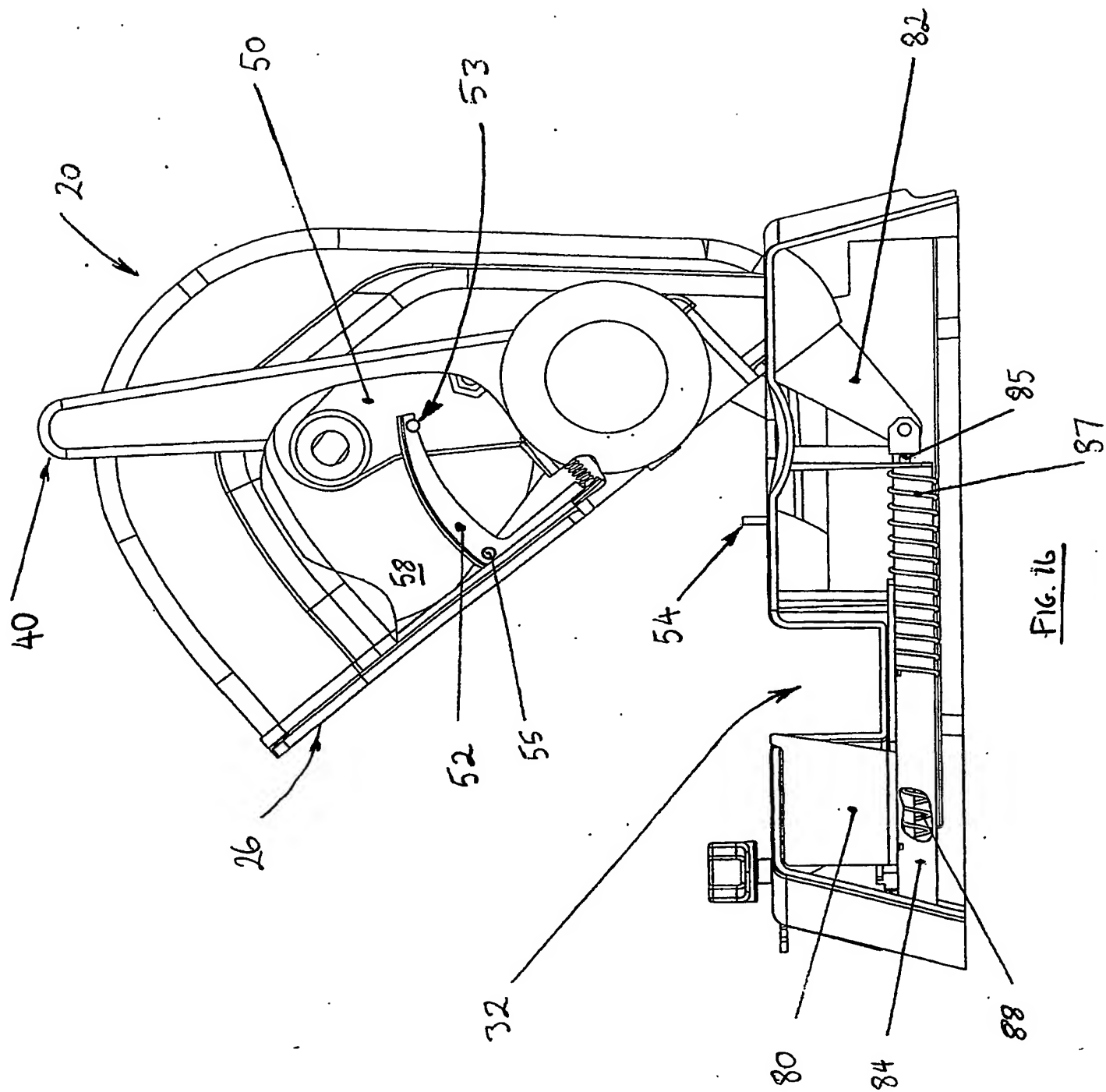


FIG. 1b



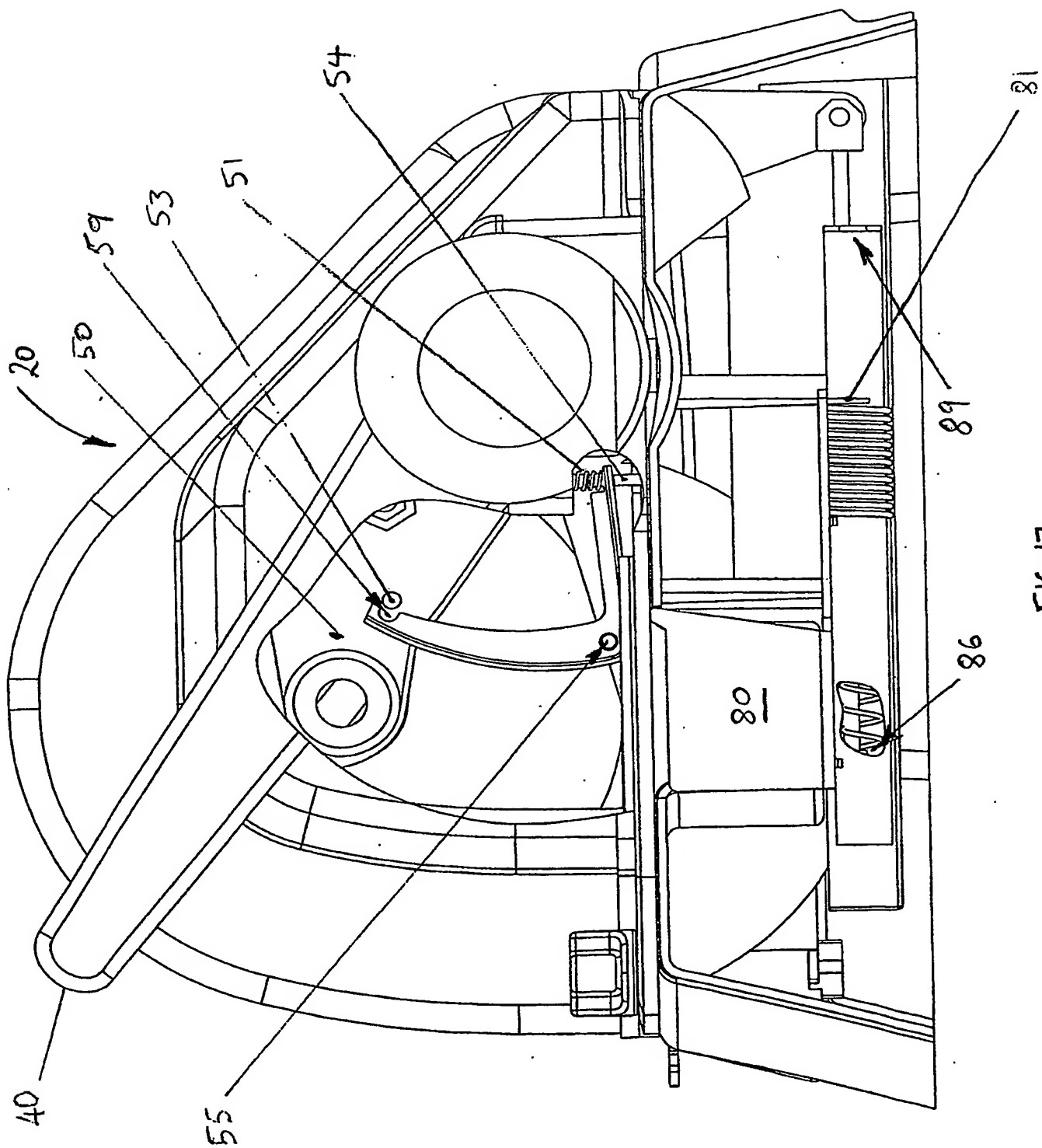


FIG. 17

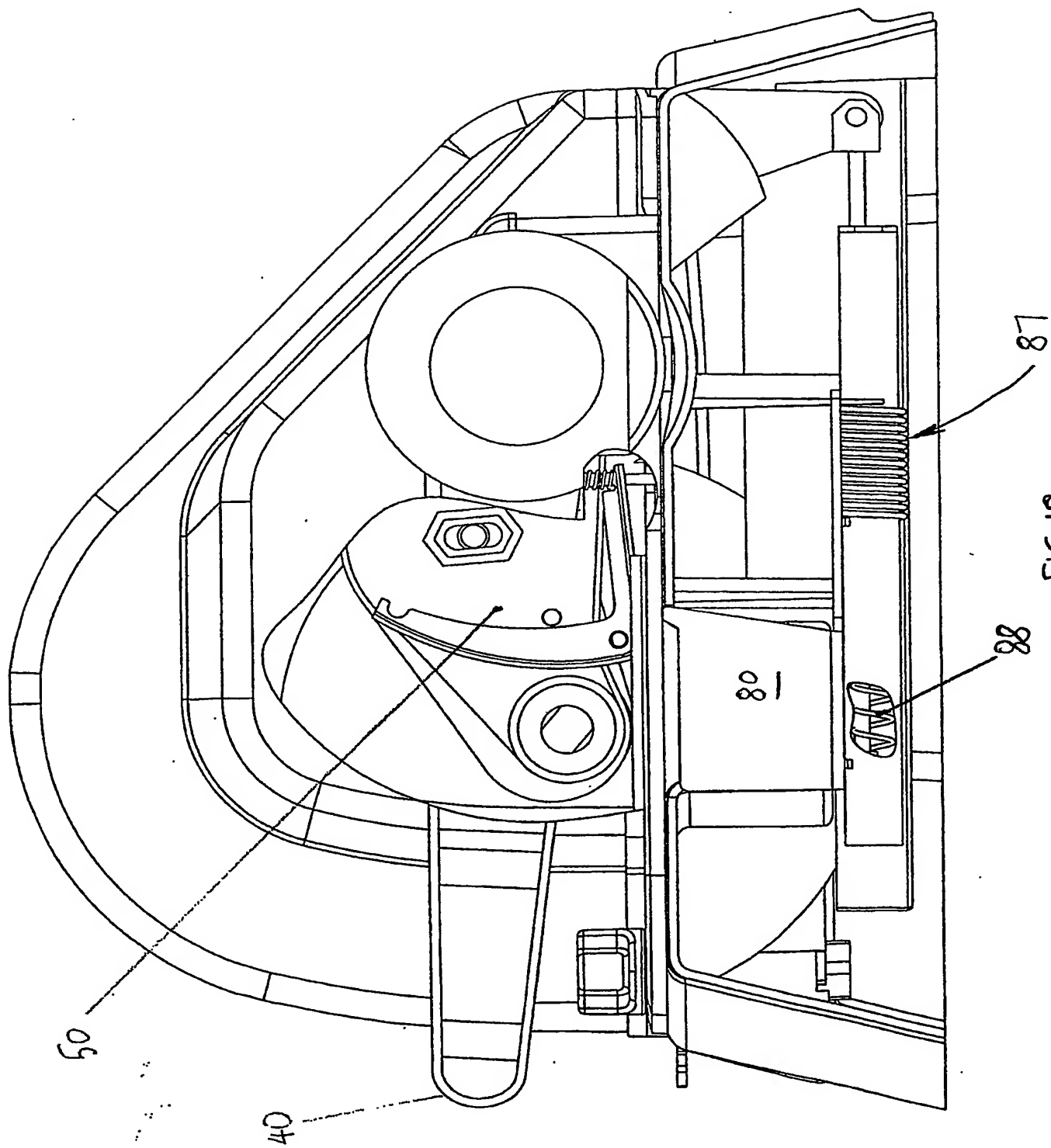


FIG. 18

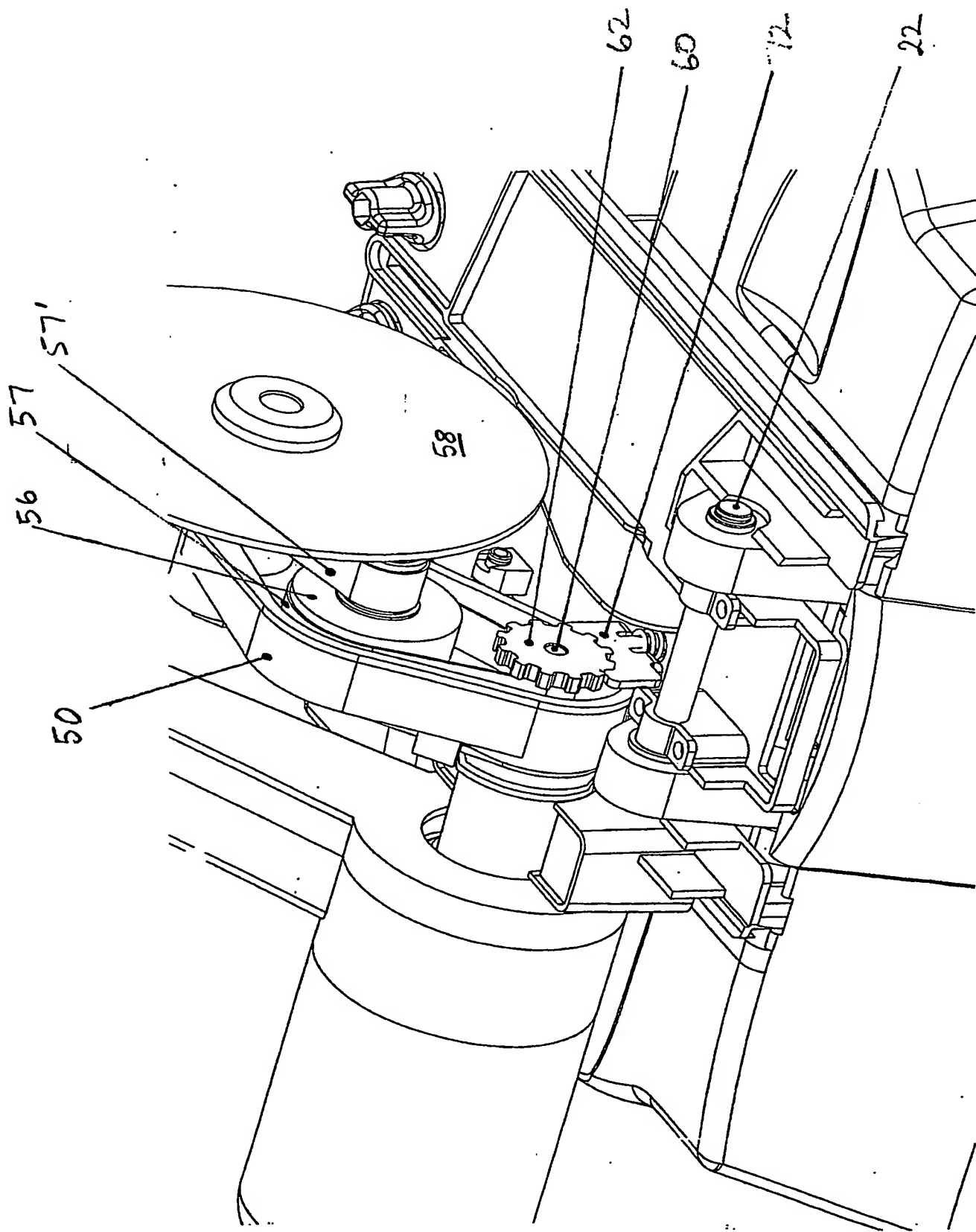


FIG. 19

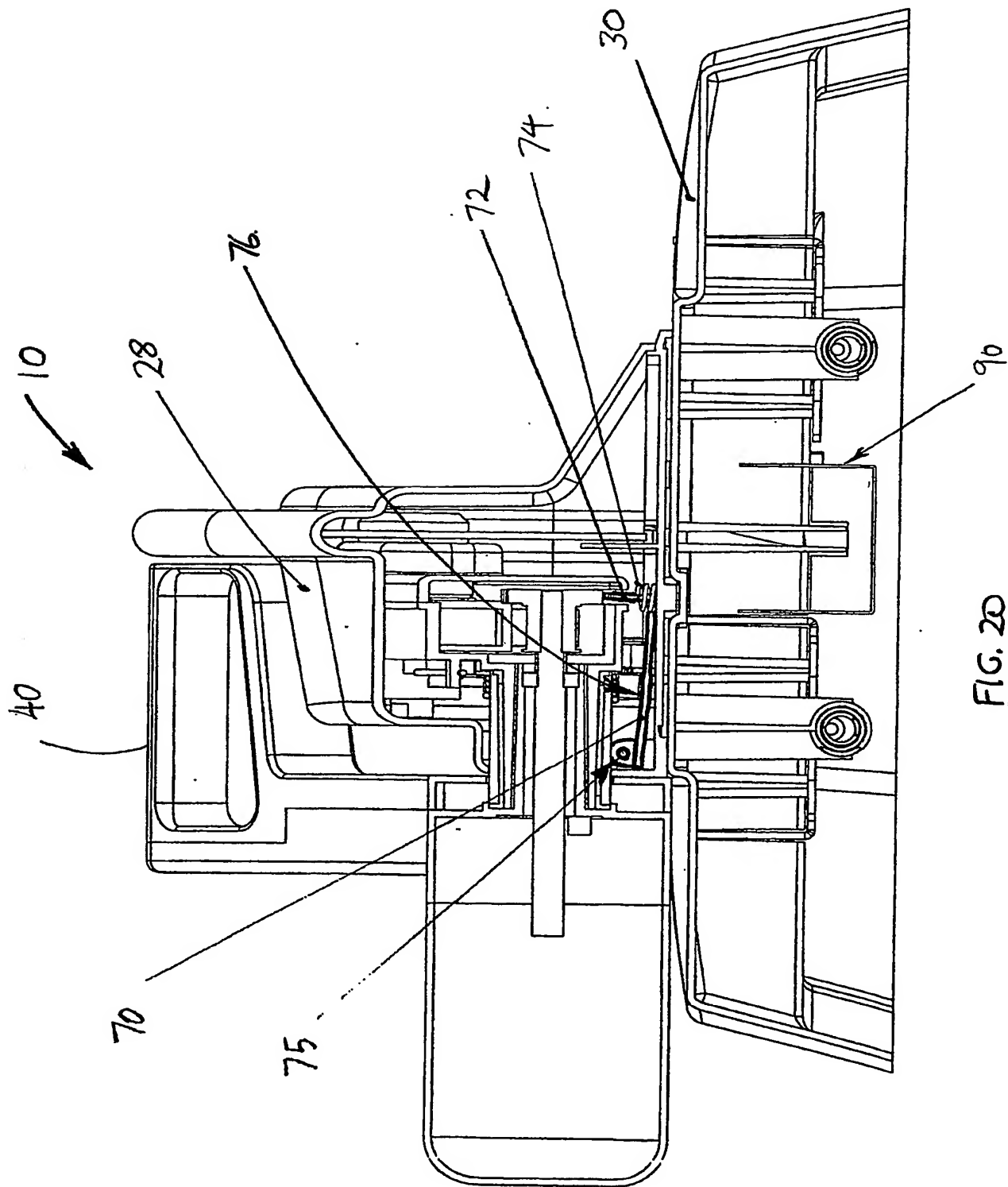


FIG. 2D

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